

## Lecture 3

### Working with Distributions

#### The distribution of a function of $X$

For example, if we know the distribution of earnings, what is the distribution of log-earnings.

If the random variable  $Y$  is defined to

$$Y = h(X)$$

then the CDF of  $Y$  is

$$F_Y(y) = P(Y \leq y) = P(h(X) \leq y)$$

The outcome space of  $Y$  is the outcome space of  $X$  transformed by  $h$ .

We usually can reexpress the last form in terms of the CDF of  $X$ .

We call  $h(x)$  a *monotone function* of  $x$ , if either  $h(x) < h(y)$  whenever  $x < y$  or  $h(x) > h(y)$  whenever  $x < y$ .

If  $h(x)$  is a monotone function of  $x$ , we can always find  $h^{-1}(x)$ , the inverse of  $h(x)$ . If  $u = h(x)$ , the value of  $h^{-1}(x)$  is just  $u$ .

In this case

$$F_Y(y) = P(X \leq h^{-1}(y)) = F(h^{-1}(y)).$$

The *uniform distribution* plays a role for distributions similar to the role played by unity for arithmetic.

Suppose we have a continuous for  $X$  and the corresponding CDF is strictly increasing when it is not zero or one (i.e., the density does not have intervals where it is zero).

Consider transforming  $X$  by the function  $F(x)$ ,

$$Z = F(X)$$

$F(x)$  gives the percentile in the distribution of  $x$ .  $F(X)$  is the percentile of a value randomly selected from the distribution.

Intuitively,  $Z$  has a uniform distribution on the outcome space  $[0, 1]$ .

**Ex.**  $X$  represents the grade of a randomly chosen person in the class

$Z = F(X)$  represents the percentile in the class that the person appeared.

Let  $U$  be a random variable with a uniform distribution. Then

$$Q(U) \sim X$$

**Ex.**  $Q(U)$  gives the exam grade corresponding to the percentile, and hence the randomly chosen class member.

## Numerical Summary Measures

Numerical measures are important properties of population distributions

The overall level of a population is often summarized by the mean, or average value.

For a discrete random variable  $X$ , the corresponding concept is that of an *expectation* or *expected value*.

$$\mathbf{E}[X] = \sum_x xP(X = x)$$

where the sum is over the outcome set.

We can also think about expectations of functions of random variables. Let  $h(x)$  be a real-valued function for  $x$  in the outcome space.

$$\mathbf{E}[h(X)] = \sum_x h(x)P(X = x)$$

For example, consider  $h(x) = |x|$  so  $\mathbf{E}[|X|]$  is the mean absolute value taken by  $X$ .

Other summary measures for probability distributions can be defined in correspondence with their population counterparts.

**Ex.** the spread of a distribution is often summarized by its *variance*,

$$\mathbb{V}[X] = \mathbf{E}[|X - \mathbf{E}[X]|^2] = \sum_x |x - \mathbf{E}[x]|^2 P(X = x)$$

where the sum is over the outcome set.

For continuous random variables the definitions of expectation and variance can be based on their probability density functions.

$$\mathbf{E}[X] = \int_{-\infty}^{\infty} x f(x) dx,$$

$$\mathbf{E}[h(X)] = \int_{-\infty}^{\infty} h(x) f(x) dx,$$

and

$$\mathbb{V}[X] = \mathbf{E}[|X - \mathbf{E}[X]|^2] = \int_{-\infty}^{\infty} |x - \mathbf{E}[x]|^2 f(x) dx.$$